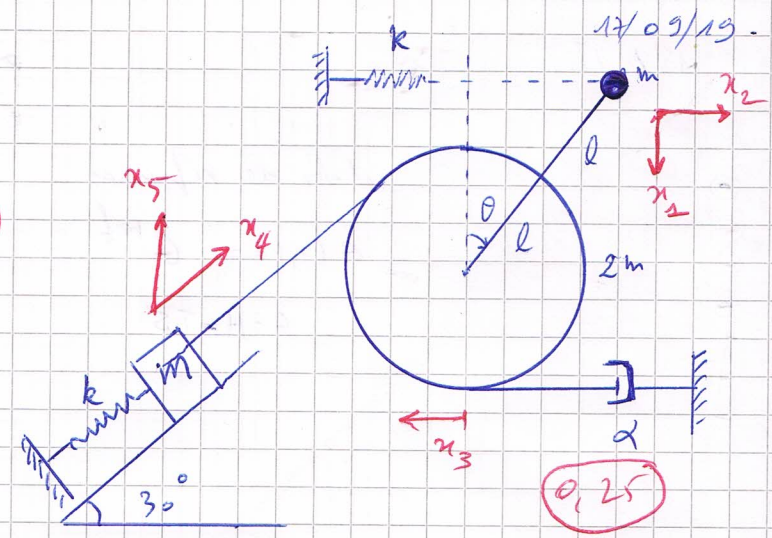


Exo 23



$$x_1 = 2l(1 - \cos\theta) \approx l\theta^2 \quad (0,25)$$

$$x_2 = 2l \sin\theta \approx 2l\theta \quad (0,25)$$

$$x_3 = l \sin\theta \approx l\theta \quad (0,15)$$

$$x_4 = l\theta \quad (0,15)$$

$$x_5 = x_4 \sin\frac{\pi}{6} = \frac{l}{2}\theta \quad (0,15)$$

1) $U = -mgx_1 + mgx_5 + \frac{k}{2}x_2^2 + \frac{k}{2}(x_3 + x_4)^2 \quad (1)$

$$U = -mg l\theta^2 + mg \frac{l}{2}\theta + \frac{k}{2}(2l\theta)^2 + \frac{k}{2}(l\theta + l\theta)^2$$

$$U = \left(\frac{5}{2}kl^2 - mgl\right)\theta^2 + \left(mg\frac{l}{2} + klx_0\right)\theta + \frac{k}{2}x_0^2 \quad (0,15)$$

2) à l'équilibre : $(\theta=0)$

$$\frac{\partial U}{\partial \theta} = 0 \Rightarrow 2\left(\frac{5}{2}kl^2 - mgl\right)\theta + \left(mg\frac{l}{2} + klx_0\right) = 0 \Rightarrow$$

$$mg\frac{l}{2} + klx_0 = 0 \Rightarrow x_0 = -\frac{mg}{2k} \quad (0,15)$$

3) Pour que l'équilibre soit stable :

$$\frac{\partial^2 U}{\partial \theta^2} > 0 \quad (0,15) \Rightarrow$$

$$5kl^2 - 2mgl > 0 \Rightarrow 5kl - 2mg > 0 \quad (0,25)$$

4) $T = \frac{1}{2}I_1\dot{\theta}^2 + \frac{1}{2}I_2\dot{\theta}^2 + \frac{1}{2}m\dot{x}_4^2 \quad (1) \quad (\ddot{x}_4 = l\ddot{\theta})$

$$I_1 = m(2l)^2 \quad ; \quad I_2 = \frac{1}{2}(2m)l^2$$

$$T = 3ml^2\dot{\theta}^2 \quad (0,15)$$

$$D = \frac{1}{2} \alpha \left(\frac{2x_0}{\partial \theta} \right)^2 \dot{\theta}^2 = \frac{1}{2} \alpha l^2 \dot{\theta}^2 \quad (0,25)$$

$$\mathcal{L} = T - U = 3ml\dot{\theta}^2 \left(\frac{5}{2} kl^2 - mgl \right) \theta^2 - \left(mg \frac{l}{2} + k(x_0) \right) \theta + \frac{k}{2} x_0^2 \quad (0,5)$$

On a l'équation de Lagrange s'écrit :

$$\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{\theta}} \right) - \frac{\partial \mathcal{L}}{\partial \theta} = - \frac{\partial D}{\partial \theta}$$

$$1) \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{\theta}} \right) = 6ml^2 \ddot{\theta} \quad (0,25)$$

$$2) \frac{\partial \mathcal{L}}{\partial \theta} = - \left(5kl^2 - mgl \right) \theta + \left(mg \frac{l}{2} + kx_0 \right) \quad (0,25)$$

$$3) \frac{\partial D}{\partial \dot{\theta}} = \alpha l^2 \dot{\theta} \quad (0,25)$$

$$6ml^2 \ddot{\theta} + (5kl^2 - mgl) \theta = - \alpha l^2 \dot{\theta} \Rightarrow$$

$$\ddot{\theta} + \frac{\alpha}{6m} \dot{\theta} + \left(\frac{5kl^2 - 2mgl}{6ml^2} \right) \theta = 0 \quad (0,5)$$

$$\lambda = \frac{\alpha}{12m}, \quad \omega_0 = \sqrt{\frac{5kl^2 - 2mgl}{6ml^2}}$$

5) Pour avoir un mouvement oscillatoire il faut être dans le régime pseudo-périodique $\Rightarrow \lambda^2 - \omega_0^2 < 0 \Rightarrow$

$$\left(\frac{\alpha}{12m} \right)^2 - \left(\frac{5kl^2 - 2mgl}{6ml^2} \right) < 0 \quad (0,5)$$