

TP-3 SIMPLE PENDULUM

The Purpose

- 1/ Study the period (T) of a simple pendulum: influence of the length (L) of the pendulum and the amplitude (angle θ) on the period of oscillations.
- 2/ Measurement of the intensity of the gravitational field using a simple pendulum.

Theoretical part

We consider a simple pendulum consisting of a material point (M) with mass m , suspended from an inextensible, massless string of length l .

This pendulum oscillates without friction (neglecting air resistance) in a vertical plane (figure opposite).

The mass m is displaced by an angle θ_0 with respect to the vertical. The second law of Newton in a Galilean reference frame is written as:

$$m \vec{\gamma} = \vec{P} + \vec{T} \dots\dots\dots (1)$$

$\vec{\gamma}=?$

In the polar coordinate system, we have:

$$\vec{v} = \frac{d \vec{r}}{dt} \quad / \quad \vec{r} = r \vec{u}_\rho$$

$$\vec{v} = \frac{d}{dt}(r \vec{u}_\rho) = \dot{r} \vec{u}_\rho + r \dot{\theta} \vec{u}_\theta \dots\dots\dots (2)$$

$$\vec{\gamma} = \frac{d^2}{dt^2}(\vec{r}) = \frac{d\vec{v}}{dt} = \frac{d}{dt}(\dot{r}\vec{u}_\rho + r\dot{\theta}\vec{u}_\theta)$$

$$\vec{\gamma} = (\ddot{r} - r\dot{\theta}^2)\vec{u}_\rho + (2\dot{r}\dot{\theta} + r\ddot{\theta})\vec{u}_\theta \dots\dots\dots (3)$$

According to (1) and (3) :

$$m[(\ddot{r} - r\dot{\theta}^2)\vec{u}_\rho + (2\dot{r}\dot{\theta} + r\ddot{\theta})\vec{u}_\theta] = (-T + P \cos \theta)\vec{u}_\rho - P \sin \theta \vec{u}_\theta \dots\dots (4)$$

With $r = L = cst \Leftrightarrow \ddot{r} = \dot{r} = 0$

So:

$$(4) \Leftrightarrow \begin{cases} mr\dot{\theta}^2 = -T + P \cos \theta & (5 - a) \\ mr\ddot{\theta} = -P \sin \theta & (5 - b) \end{cases}$$

For weak oscillations ($\theta \leq 10^\circ$): $\sin \theta = \theta$ (rad).

so:

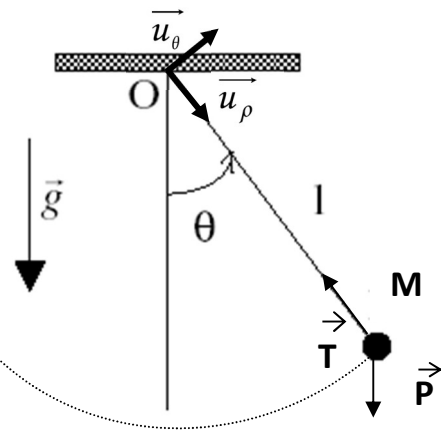
$$(5 - b) \Leftrightarrow mr\ddot{\theta} + mg\theta = 0 \Leftrightarrow L\ddot{\theta} + g\theta = 0 \Leftrightarrow \ddot{\theta} + \frac{g}{L}\theta = 0 \quad \text{on pose } \omega^2 = \frac{g}{L} \quad \text{we will have}$$

the differential equation: $\ddot{\theta} + \omega^2\theta = 0 \quad (6)$

Whose general solution is: $\theta(t) = \theta_1 \cos \omega t + \theta_2 \sin \omega t$

For $\theta(t=0) = \theta_0 \Leftrightarrow \theta_1 = \theta_0$ with $v(t=0) = 0 \Leftrightarrow [r\dot{\theta}(t)]_{t=0} = 0$

$$\Leftrightarrow r[-\theta_1 \sin \omega t + \theta_2 \cos \omega t]_{t=0} \quad \text{that is } \theta_2 = 0$$



Therefore $\theta(t) = \theta_0 \cos \omega t \Leftrightarrow \theta(t) = \theta_0 \cos \frac{g}{L}t$ (7)

This is the case of harmonic oscillatory motion, with its period given by:

$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{L}{g}}$ (8)

Experiment

I/ Influence of the pendulum's length on the period

Attach a mass m to the pendulum ($m = 33g$).

Oscillate the pendulum with a fixed angle θ_0 ($\theta_0 \leq 10^\circ$), measure the time ($t = nT$), then calculate the period for various lengths of the string and for two numbers of oscillations ($n_1=10$ et $n_2=30$).

Record the results in **Table 1**.

$\theta_0=7^\circ, n_1=10, n_2=30$				
L (cm)	20	40	70	100
$t_1=n_1T_1(s)$				
$T_1(s)$				
$T_1^2 (s^2)$				

Table 1

1/ Plot the graph $L \left(\frac{T^2}{4\pi^2} \right)$ and determine the average value of g and calculate its uncertainty with $\delta t = 0.02s$ and $\delta l = 0.001m$.

2/ Compare the results of the period T and the value of g for n_1 and n_2 . What can you conclude ?

II/ Influence of the angle on the period

Attach a mass m to the pendulum at a length L ($L = 40$ cm).

Spread the pendulum with different angles θ_0 and release it without initial speed and measure the time t and calculate the period of the oscillations (for n_1 and n_2 oscillations).

Record the results in Table 2.

$L = 40$ cm , $n_1=10$, $n_2=30$					
$\theta_0(^\circ)$	6	8	10	30	90
$t_1=n_1T_1(s)$					
$T_1(s)$					

Table 2

1/ Calculate g analytically for the angles that allow the application of the formula $T = 2\pi \sqrt{\frac{L}{g}}$, and calculate its uncertainty.

2/ Does the angle variation θ_0° influence T and g ? Interpret the results.

- Conclusion